

# Tree-cut Width: Computation and Algorithmic Applications

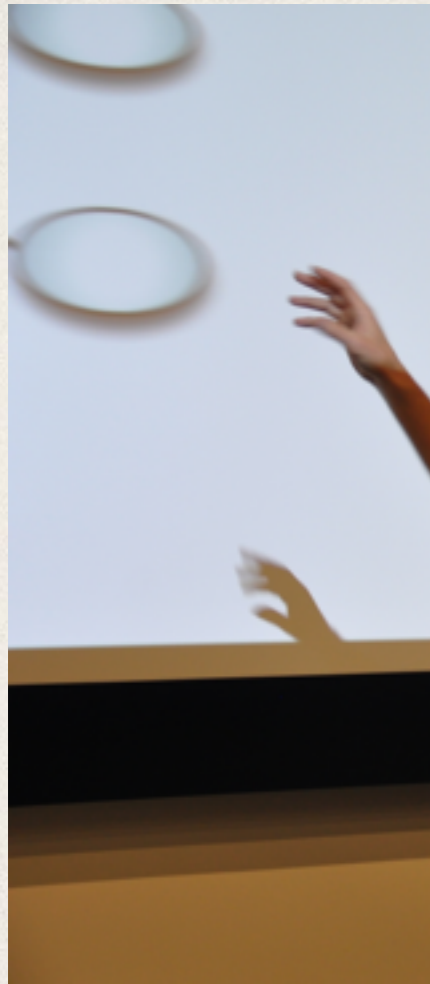
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AGTAC, Koper, Slovenia  
17 June 2015

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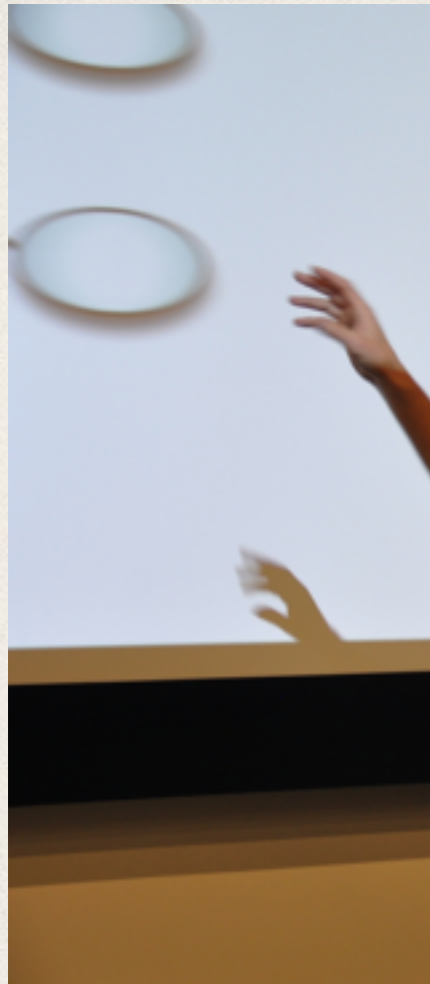


Tree-cut width proposed by Paul Wollan, 2013



Tree-cut width

Algorithmic application of tree-cut width  
joint-work with Robert Ganian and Stefan Szeider.



Tree-cut wic



Constructing a tree-cut decomposition  
joint-work with Sang-il Oum, Christophe  
Paul, Ignasi Sau and Dimitrios Thilikos.

Algorithm  
joint-work wit



# Tree-cut decomposition

[Marx&Wollan 2014, Wollan 2015]

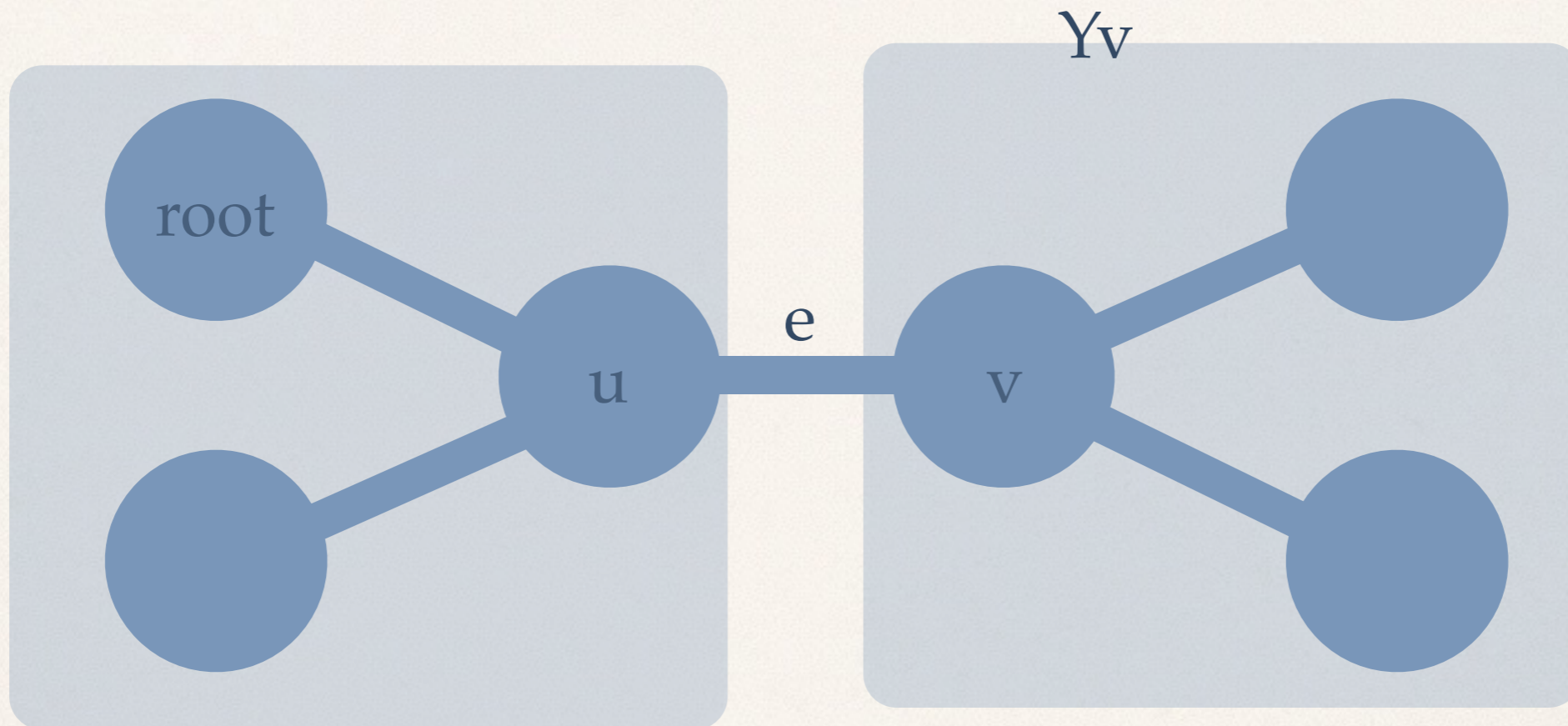
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$(T, \chi = \{X_t, t \in V(T)\})$  is a tree-cut decomposition of  $G$   
if

- $T$  is a tree
- $\chi$  forms a near-partition of  $V(G)$

# Tree-cut width: (1) cut

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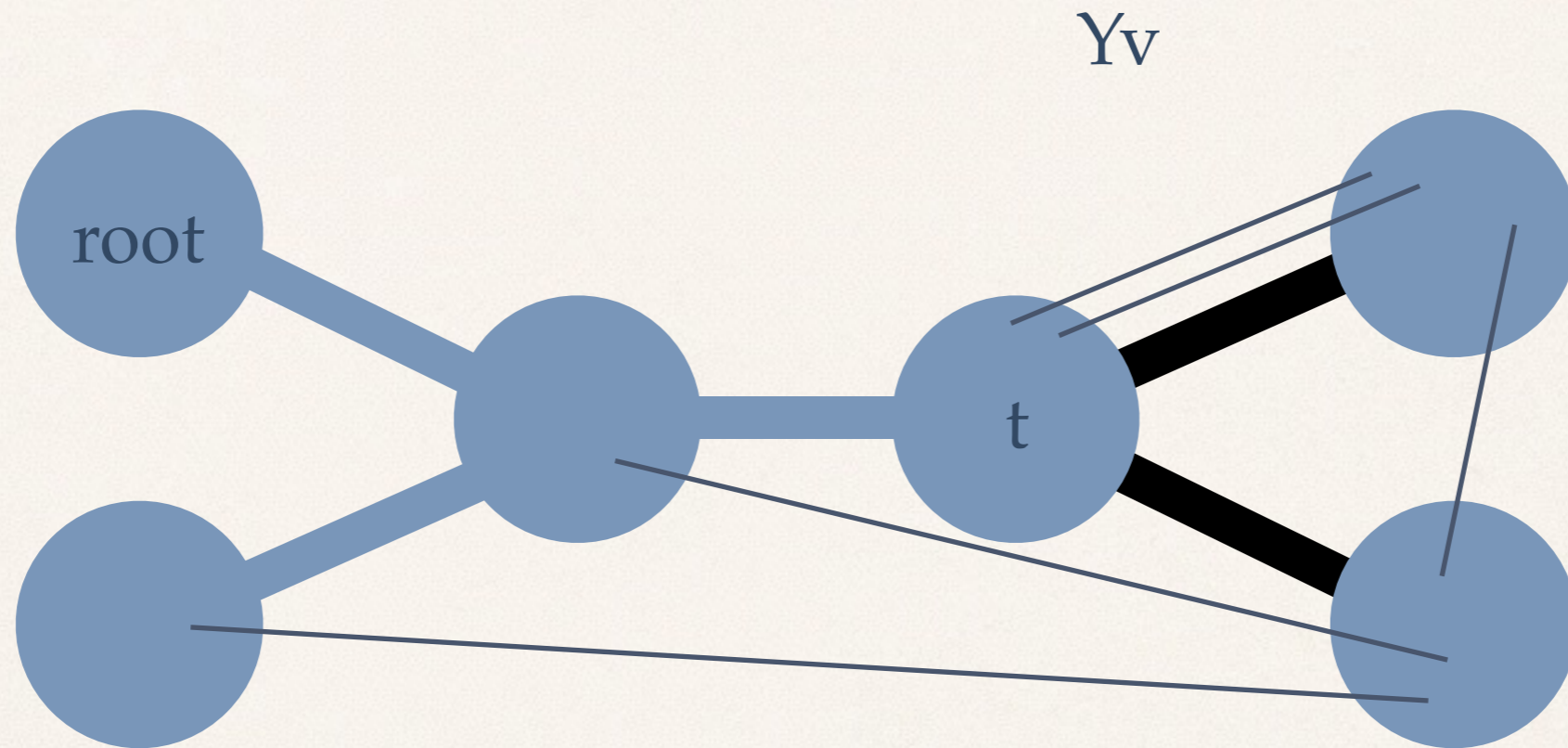


$\text{cut}(e) =$  the set of edges with one point in  $Y_v$  and another in  $V(G) - Y_v$

# Tree-cut width: (2) torso

3-edge-connected case

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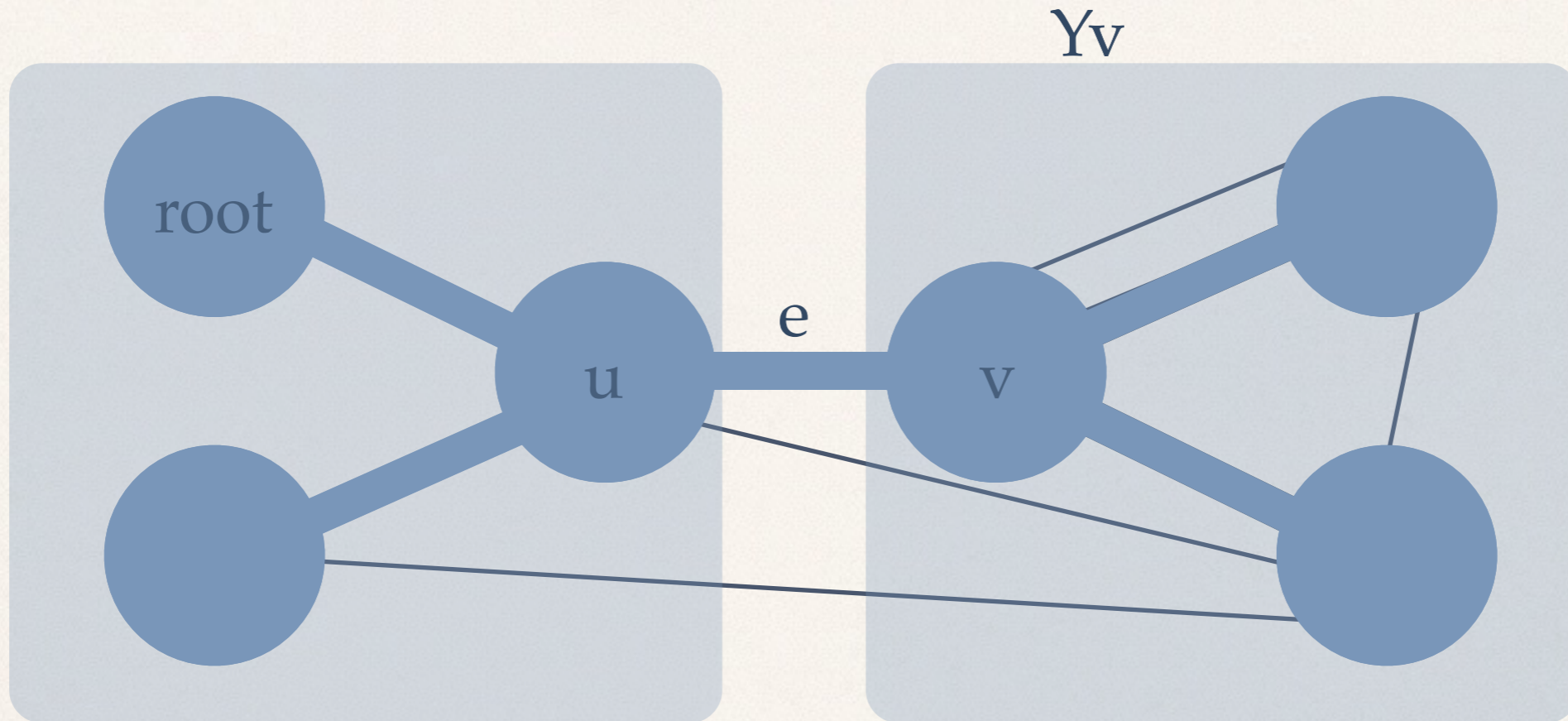
$R_t$  = all neighboring tree nodes of  $t$

$$|\text{torso}(t)| = |X_t| + |R_t|$$

# Tree-cut width: (3) width

3-edge-connected case

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$\text{cut}(e) =$  the set of edges with one point in  $Y_v$  and another in  $V(G) - Y_v$

$R_t =$  all neighboring tree nodes of  $t$

$$|\text{torso}(t)| = |X_t| + |R_t|$$



# Tree-cut width: (3) width

3-edge-connected case

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$Y_v$

$$\text{width}(T, \chi) = \max \{ |\text{cut}(e)|, |\text{torso}(t)| \}$$
$$\text{tcw}(G) = \min \text{width}(T, \chi)$$

$\text{cut}(e)$  = the set of edges with one point in  $Y_v$  and another in  $V(G) - Y_v$

$R_t$  = all neighboring tree nodes of  $t$

$$\text{torso}(t) = |X_t| + |R_t|$$

# Tree-cut width: (3) width

general case

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$Y_v$

$$\text{tcw}(G) = \max \text{tcw}(G_i)$$

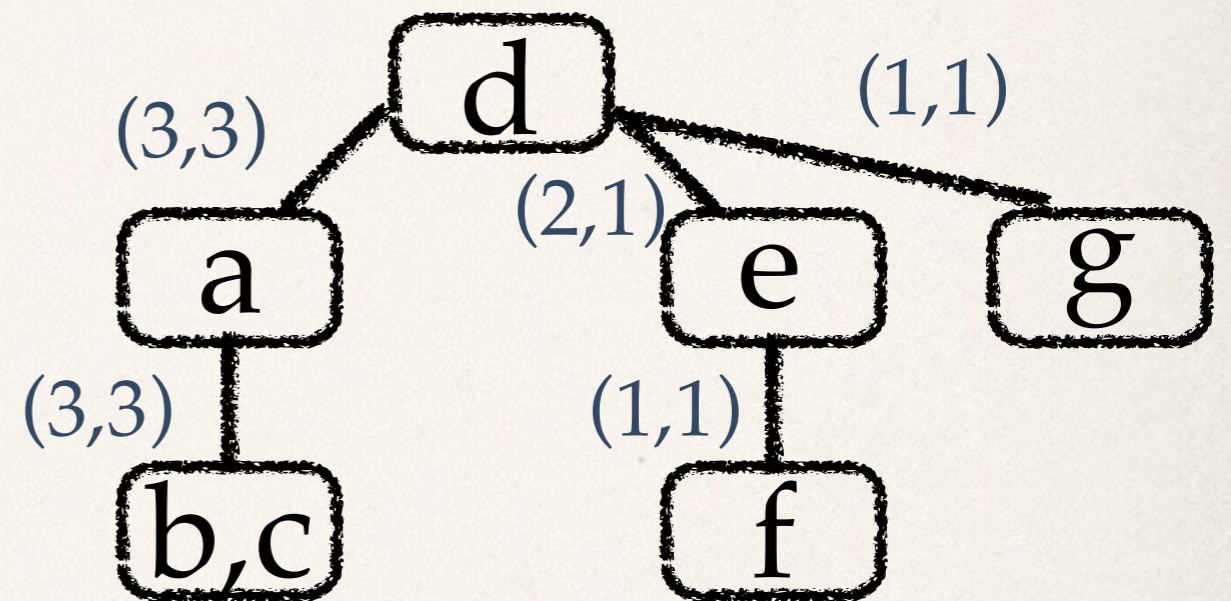
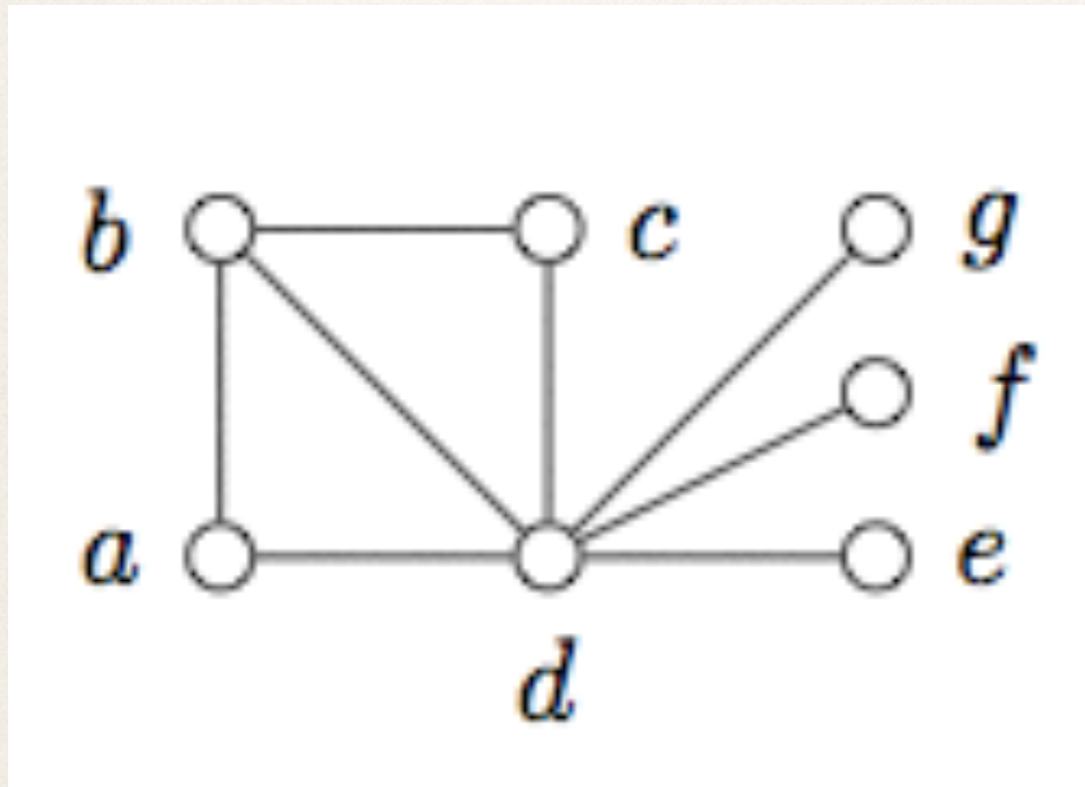
$G_i$ 's are maximal 3-edge connected subgraphs

$\text{cut}(e) =$  the set of edges with one point in  $Y_v$  and another in  $V(G)-Y_v$

$R_t =$  all neighboring tree nodes of  $t$

$$\text{torso}(t) = |X_t| + |R_t|$$

# Tree-cut width: (4) example

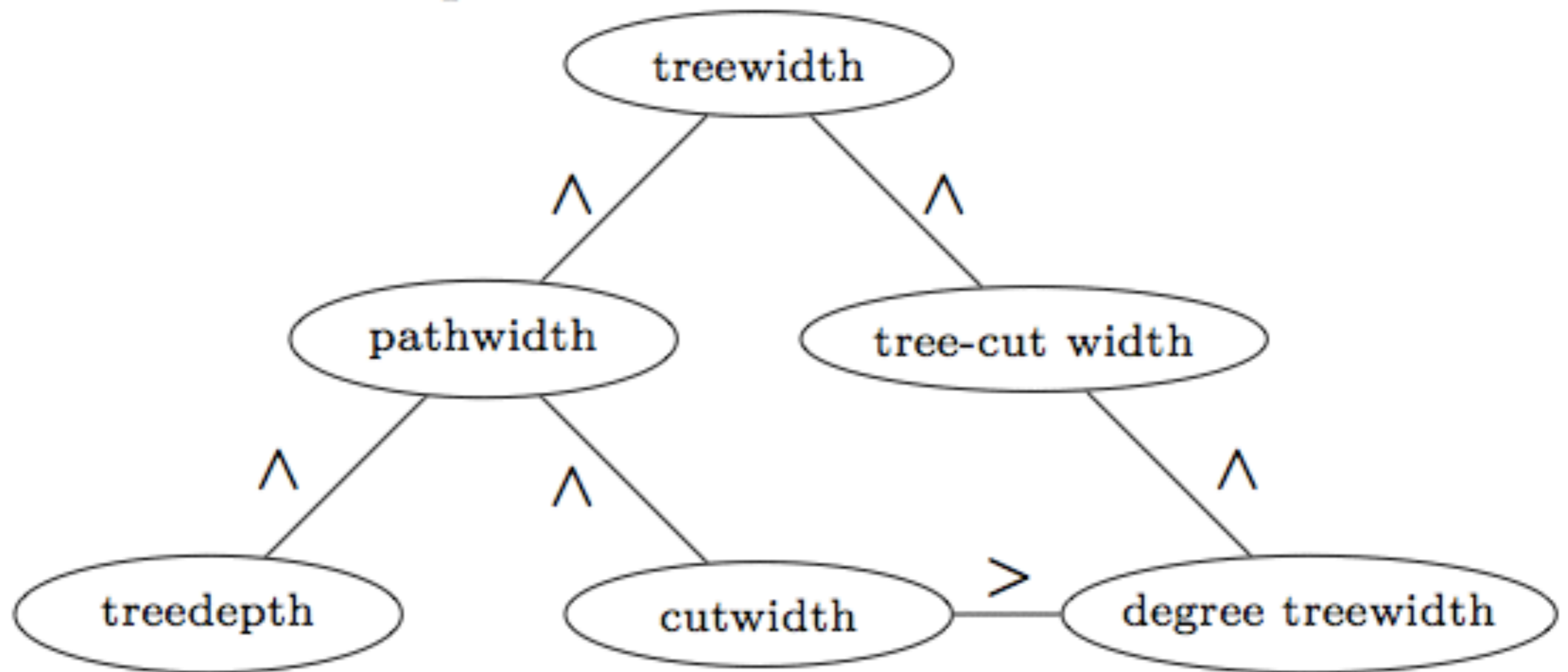


$\text{cut}(t) = \text{cut}(e)$  where  $e=(t,p(t))$

width = 3

# Relations with other width measures

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# Tree-cut width for algorithms?

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- \* Tree decomposition turned out to be a successful tool for algorithms design
- \* How about tree-cut decomposition?
  - \*  $tw = O(tcw^2)$ : having small  $tcw$  is stronger than small  $tw$
  - \* Intractable problems on graph with small  $tw$  may have hope on graph with small  $tcw$

# Algorithmic applications

with Robert Ganian and Stefan Szeider

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<i>Problem</i>	<i>Parameter</i>		
	<i>treewidth</i>	<i>tree-cut width</i>	<i>max-degree and treewidth</i>
CAPACITATED VERTEX COVER	W[1]-hard <sup>[7]</sup>	FPT <sup>(Thm 9)</sup>	FPT
CAPACITATED DOMINATING SET	W[1]-hard <sup>[7]</sup>	FPT <sup>(Thm 23)</sup>	FPT
IMBALANCE	Open <sup>[28]</sup>	FPT <sup>(Thm 16)</sup>	FPT <sup>[28]</sup>
LIST COLORING	W[1]-hard <sup>[11]</sup>	W[1]-hard <sup>(Thm 24)</sup>	FPT <sup>(Obs 4)</sup>
PRECOLORING EXTENSION	W[1]-hard <sup>[11]</sup>	W[1]-hard <sup>(Thm 24)</sup>	FPT <sup>(Obs 4)</sup>
BOOLEAN CSP	W[1]-hard <sup>[35]</sup>	W[1]-hard <sup>(Thm 25)</sup>	FPT <sup>[35]</sup>

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FPT w.r.t. parameter  $k$  means there is a  $f(k)\text{poly}(n)$ -algorithm.

W[1]-hard means  $f(k)\text{poly}(n)$ -algorithm is unlikely.

# Computing a tree-cut decomposition

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- \* QUEST: design an algorithm which answers the question exactly
  - \* Given a graph  $G$ : produce a tree-cut decomposition of width at most  $k$  or declare that  $\text{tcw} > k$ .
- \* ...and which runs as quickly as possible

- ❖ Deciding if  $tcw \leq k$  is NP-complete: from min bisection
- ❖ Exact computation: non-uniform, non-constructive
  - ❖ Graphs of  $tcw \leq k$  are closed under immersion [Wollan 2015]
  - ❖ Graphs are w.q.o. under immersion [N.Robertson, P.D.Seymour 2010]
  - ❖ W.Q.O. of immersion implies a finite characterization by forbidden immersions. [N.Robertson, P.D.Seymour 2010]
  - ❖ Immersion testing can be done in  $f(k)\text{poly}(n)$   
[M. Grohe, K.-i. Kawarabayashi, D. Marx, and P. Wollan 2011]
- ❖ Approximation
  - ❖ 2-approximation in time  $2^{O(k^2 \cdot \log k)} \cdot n^2$   
[by E.J.Kim, S.Oum, C.Paul, D.Thilikos, I.Sau 2015]



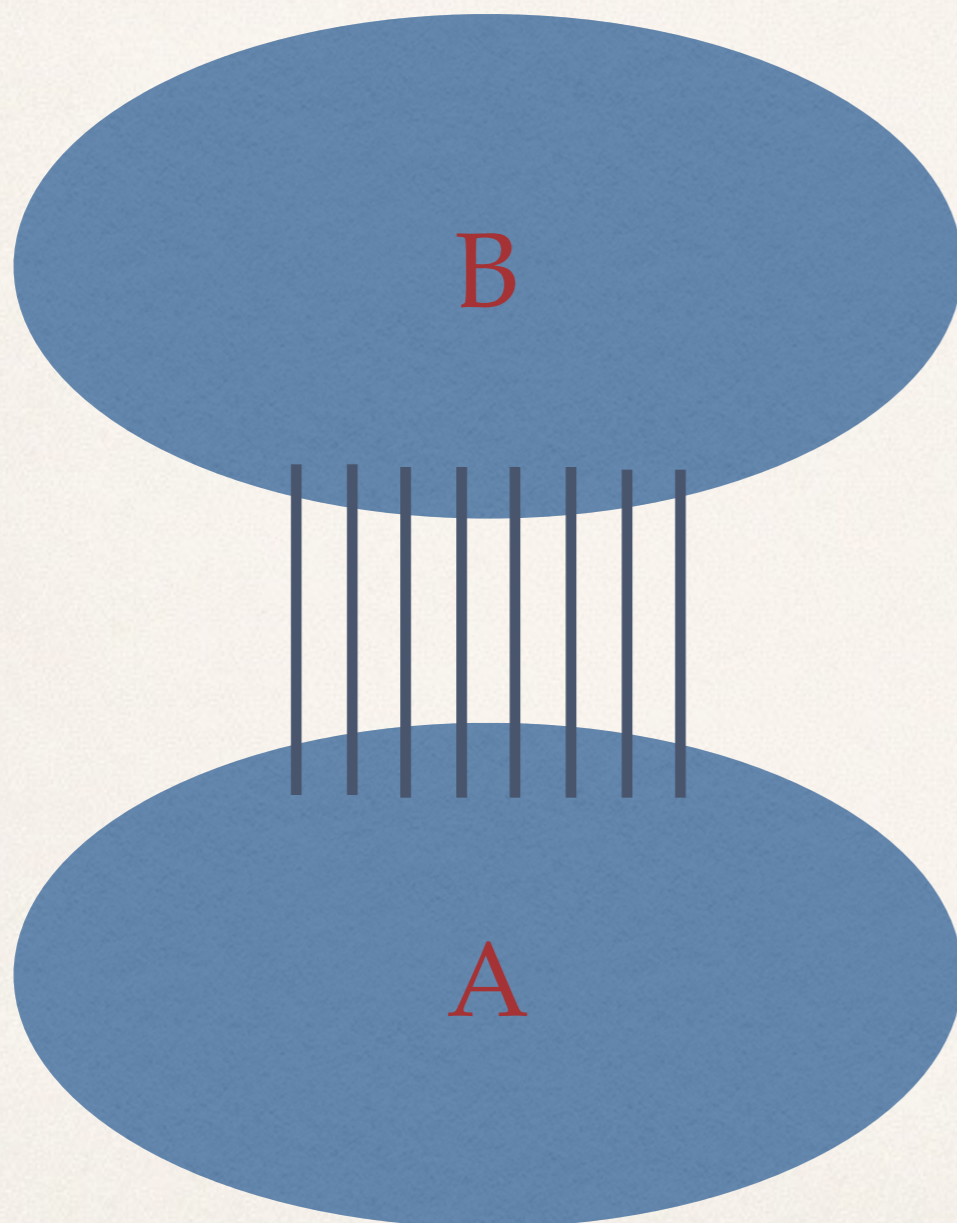
# Computing a tree-cut decomposition

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- \* QUEST: design an algorithm which answers the question ~~exactly~~ **approximately**
- \* Given a graph  $G$ : produce a tree-cut decomposition of width at most  ~~$k$~~   **$2k$**  or declare that  $\text{tcw} > k$ .
- \* ...and which runs as quickly as possible.

# Sketch of our algorithm

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- Find a random cut (A,B) of size  $\leq 2k$
- This corresponds to a decomposition

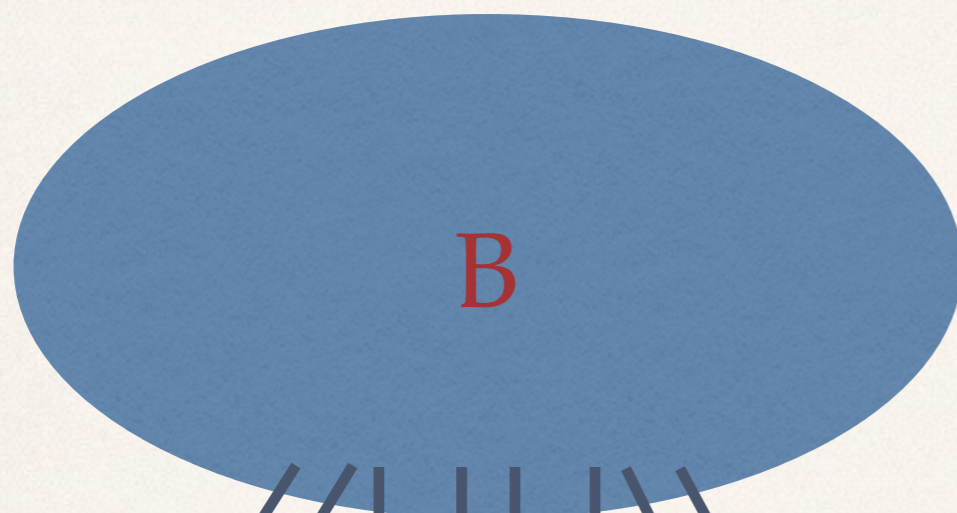


$(T, \chi = \{X_t, t \in V(T)\})$

- Currently, too large bags.
- Idea: “**Grow**” the tree,  
“**Reduce**” the bag sizes.

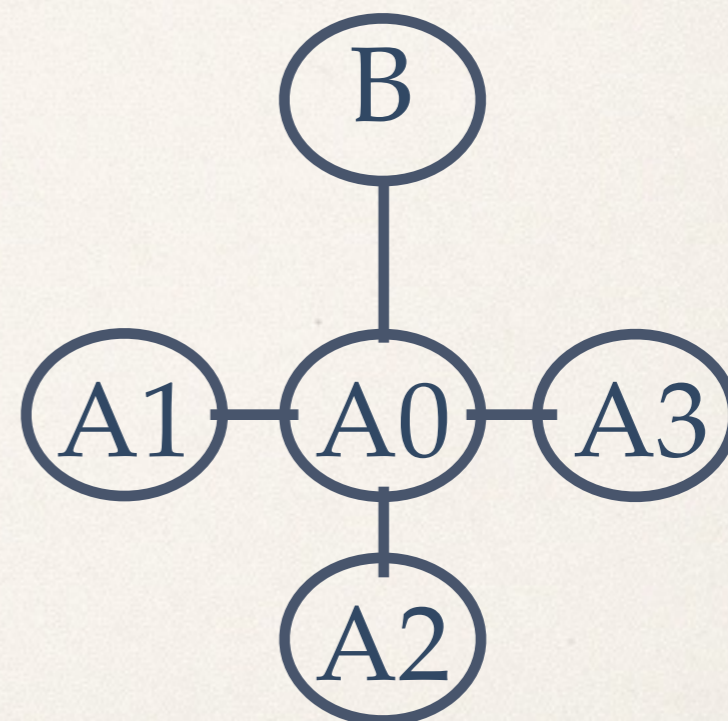
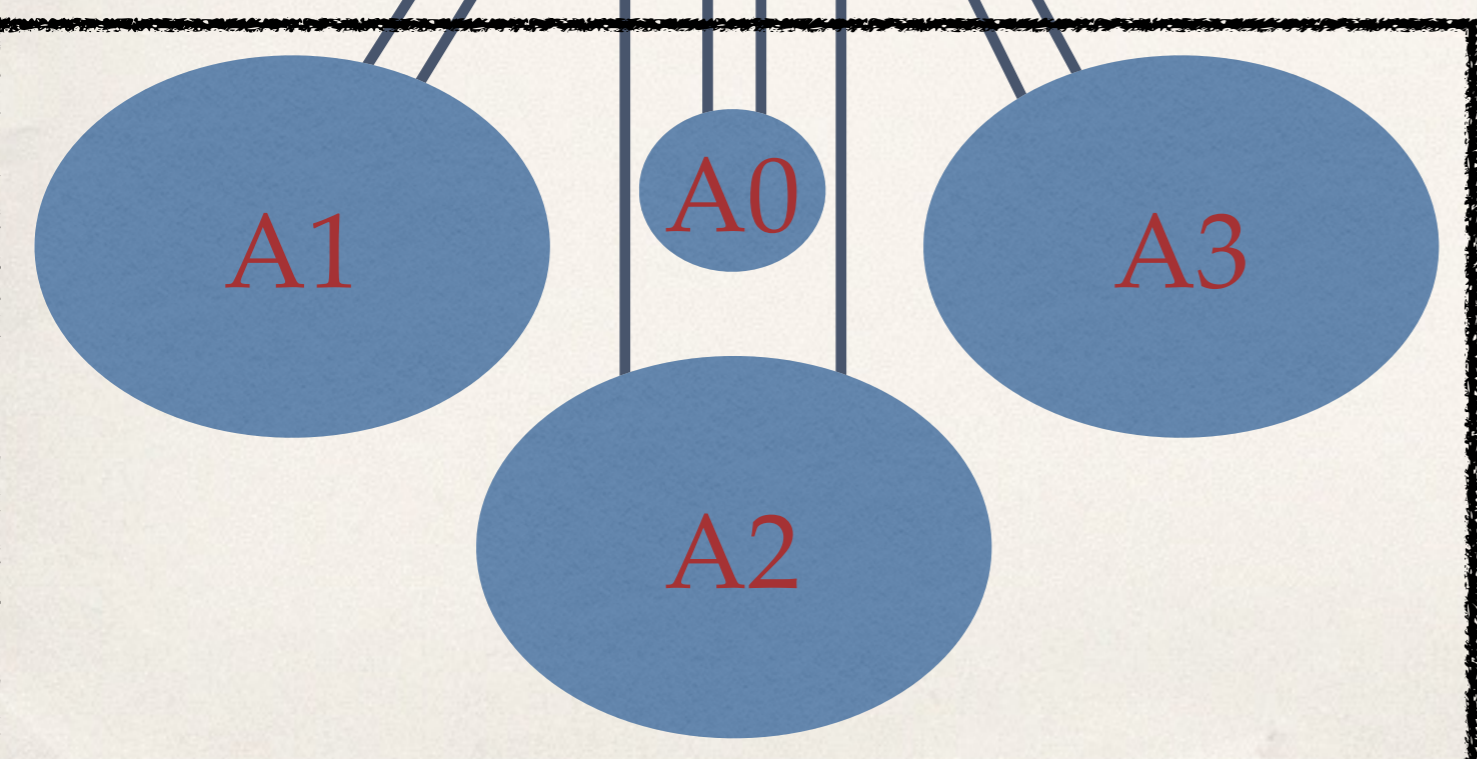
# Sketch of our algorithm

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- Find a partition of A meeting a set of conditions (\*)
- If such a partition exists - refine A

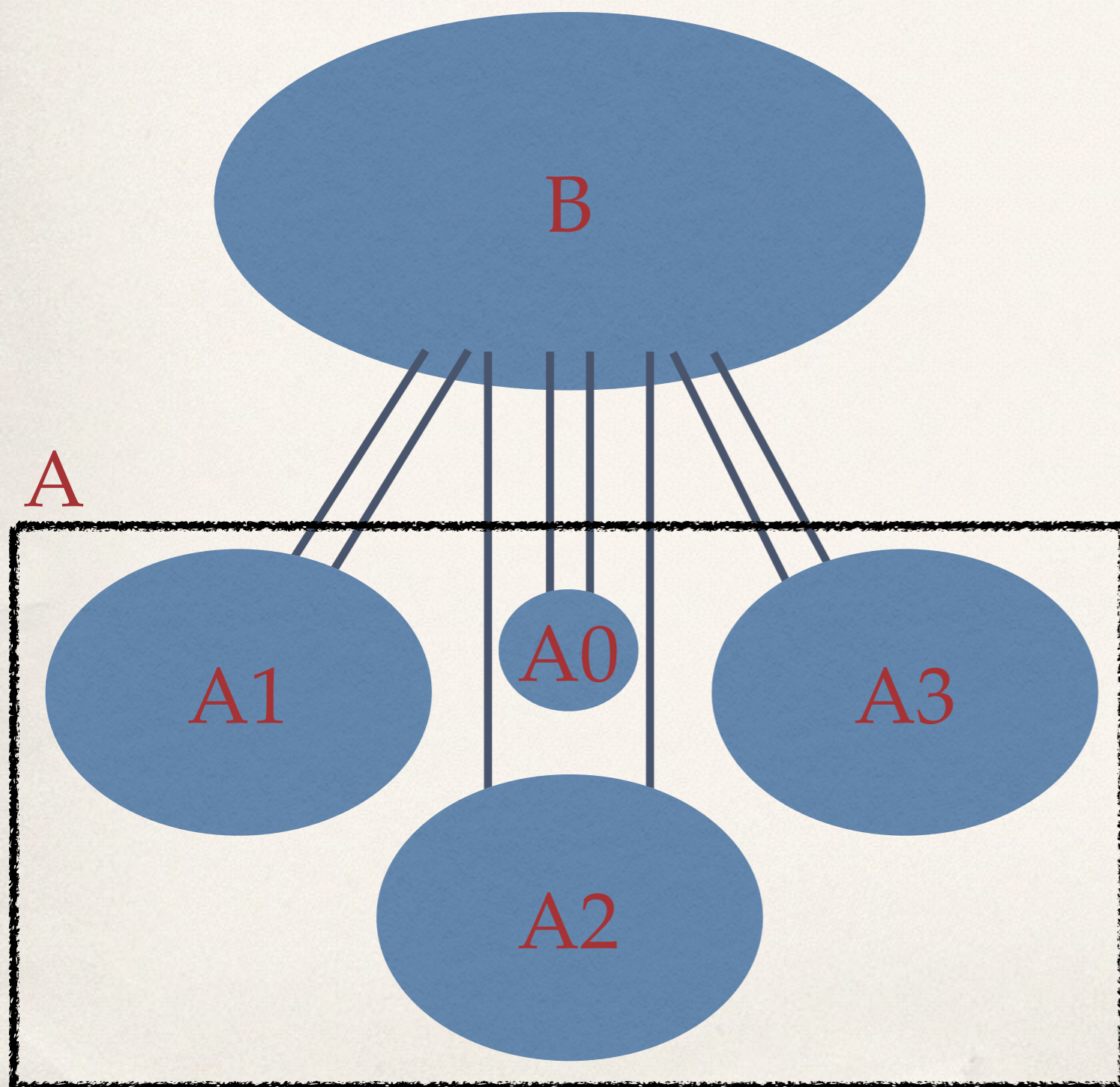
A



$(T, \chi = \{X_t, t \in V(T)\})$

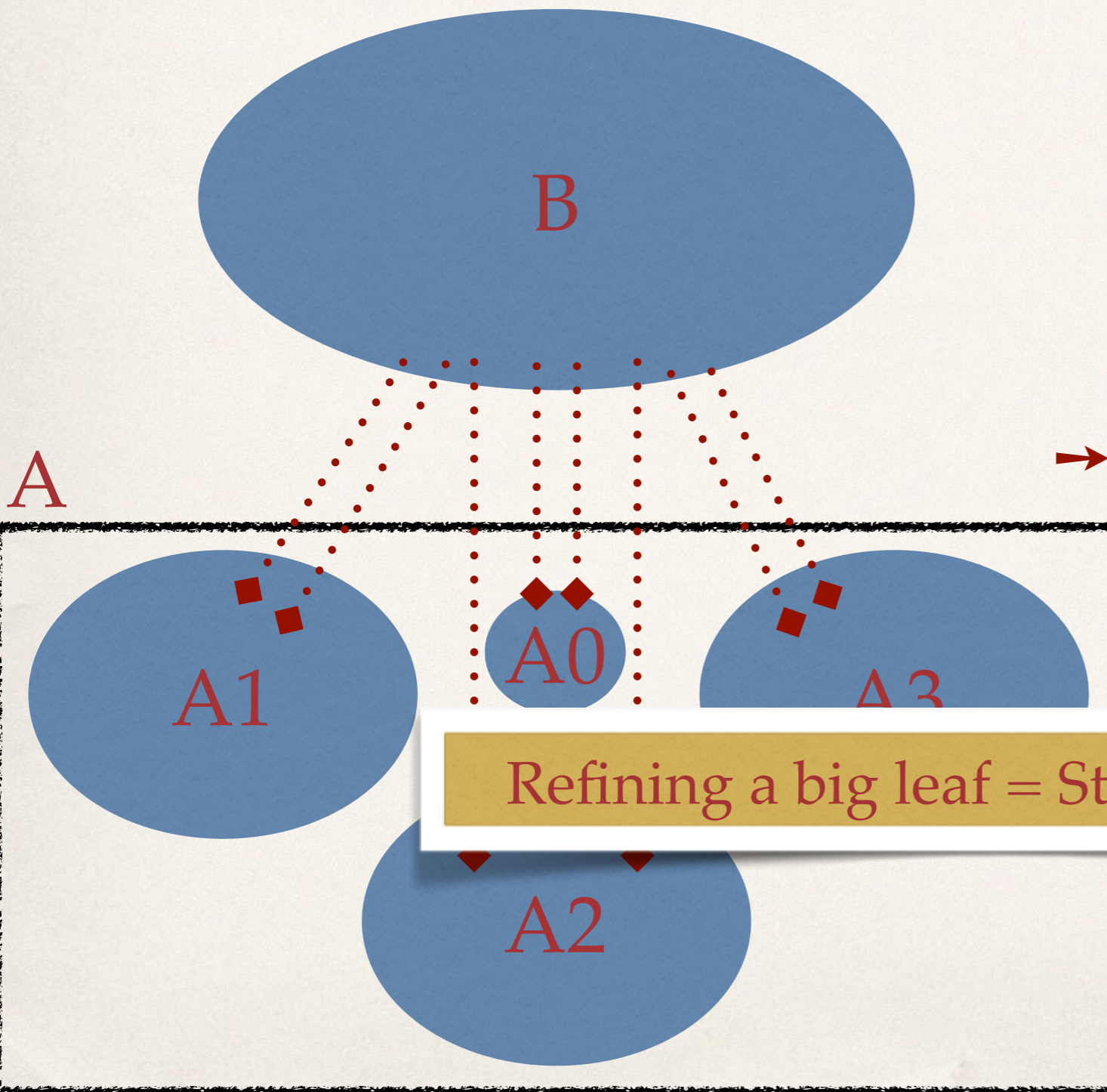
# Sketch of our algorithm

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- Find a partition of  $A$  such that
- $\text{cut}(A_i, A \setminus A_i) \leq k, i \in \{1, 2, 3\}$
  - $\text{cut}(A_i, B) \leq k$
  - $|A_0| + \text{number of parts} \leq k$

# Sketch of our algorithm



Find a partition of A such that

-  $\text{cut}(A_i, A \setminus A_i) \leq k, i \in \{1, 2, 3\}$

~~-  $\text{cut}(A_i, B) \leq k$~~

- number of parts  $\leq k$

→ each part  $A_i$  has  $\leq k$  "terminals"

Refining a big leaf = Star-Cut Problem

# Algorithm for Star-Cut

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- ❖ Fact

- $tw \leq 3tcv$
- 5-approx

Iteratively solve Star-cut to refine the initial tree-cut decomposition.

[Gendler et al. 2013]

- ❖ Algorithm

1. Run Bo
2. Dynam

The entire routine runs in

$$k^{O(k^2)} \cdot n \cdot n$$

$r > k$

most  $15k^2$

- for each of  $15k^2$  vertices, guess 'i' s.t.  $v$  belongs to  $A_i$
- keep track of #cut  $(A_i, A \setminus A_i)$  and #terminals in  $A_i$
- runtime:  $k^{(bagsize)} \cdot n$

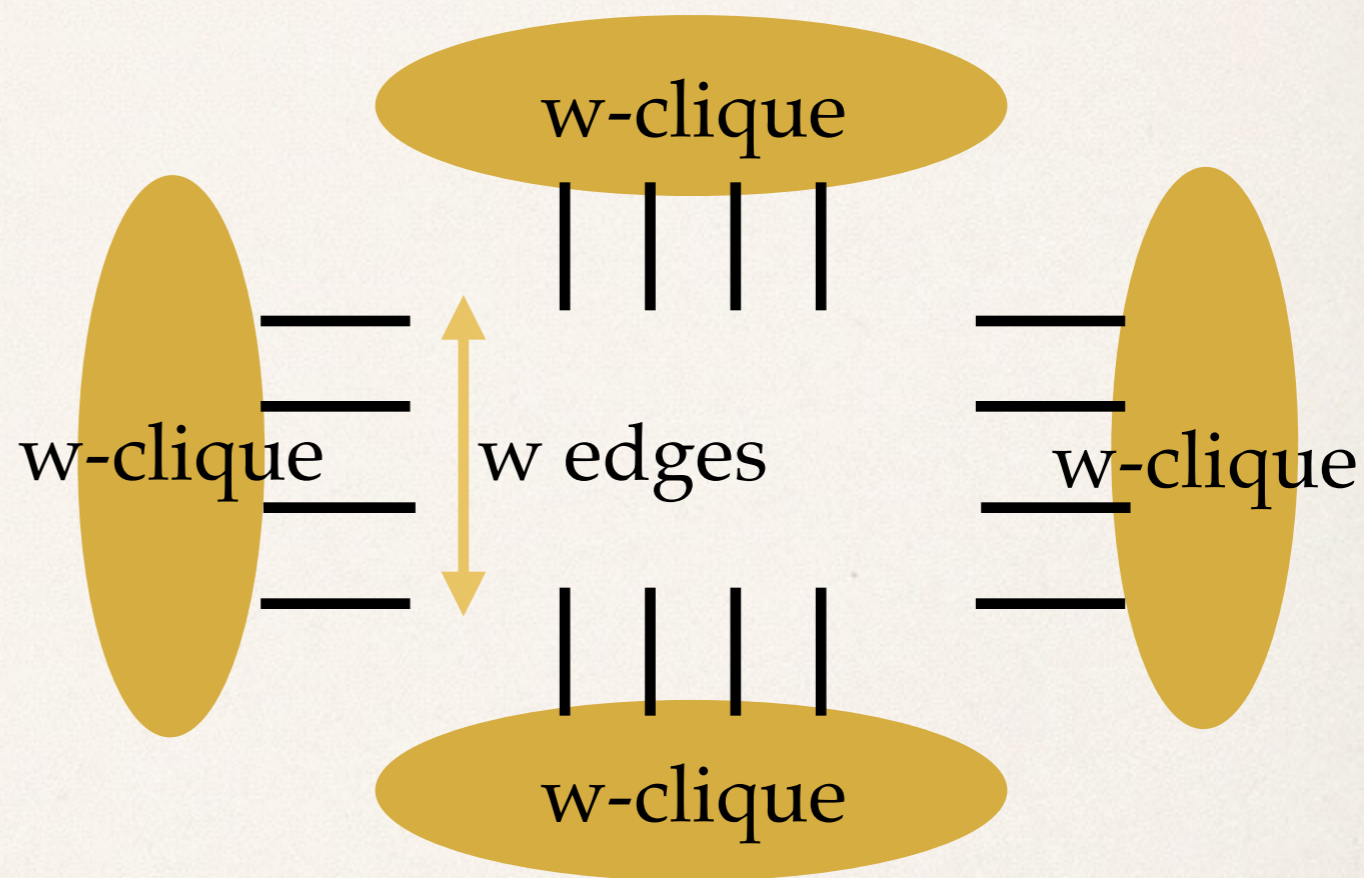
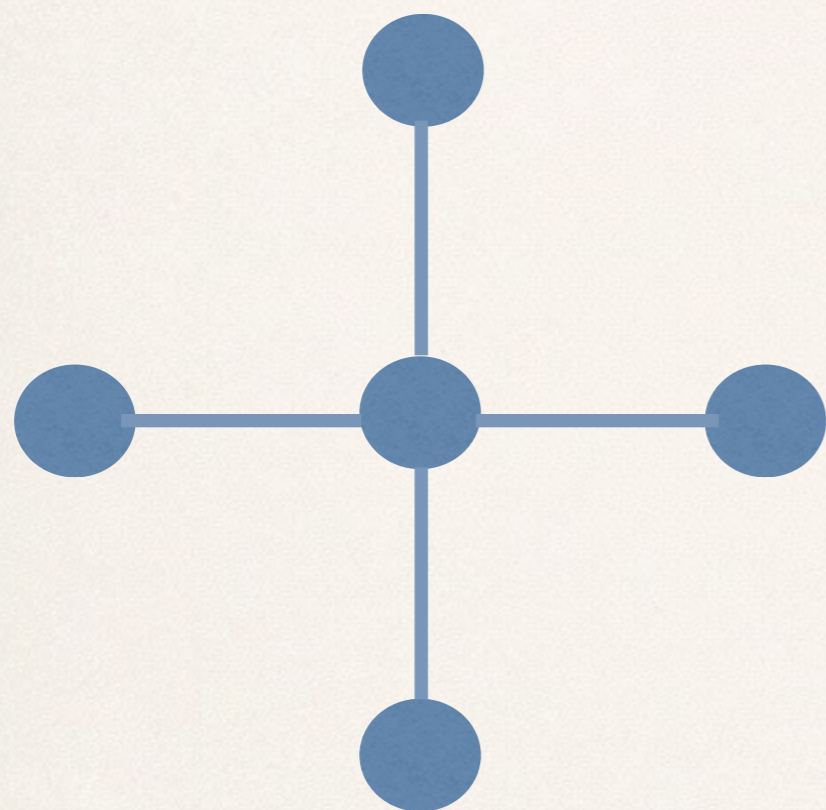
# Tree-cut width vs treewidth

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- \* Can the above algorithm be improved? DP can be improved?
- \*  $tw = O(tcw^2)$ : in fact the binding function is tight.
- \* There is an infinite family of graphs whose tree-cut width is  $w$ , and treewidth is  $\Omega(tcw^2)$ .

# Graphs with $tw = \Omega(tcw^2)$

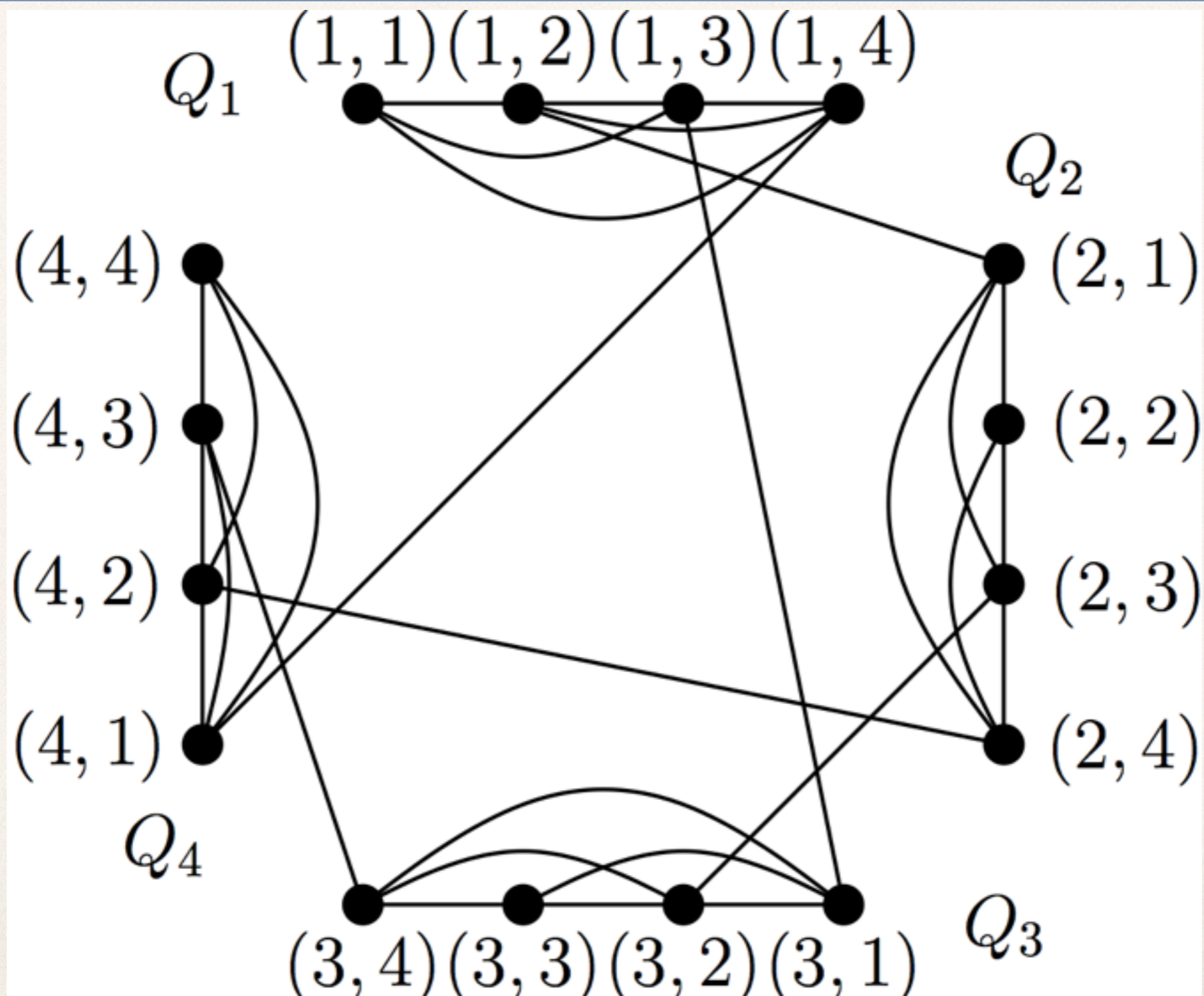
We want to build a graph with tree-cut width  $w+1$



...which looks as simple as possible, while its treewidth is as large as possible.

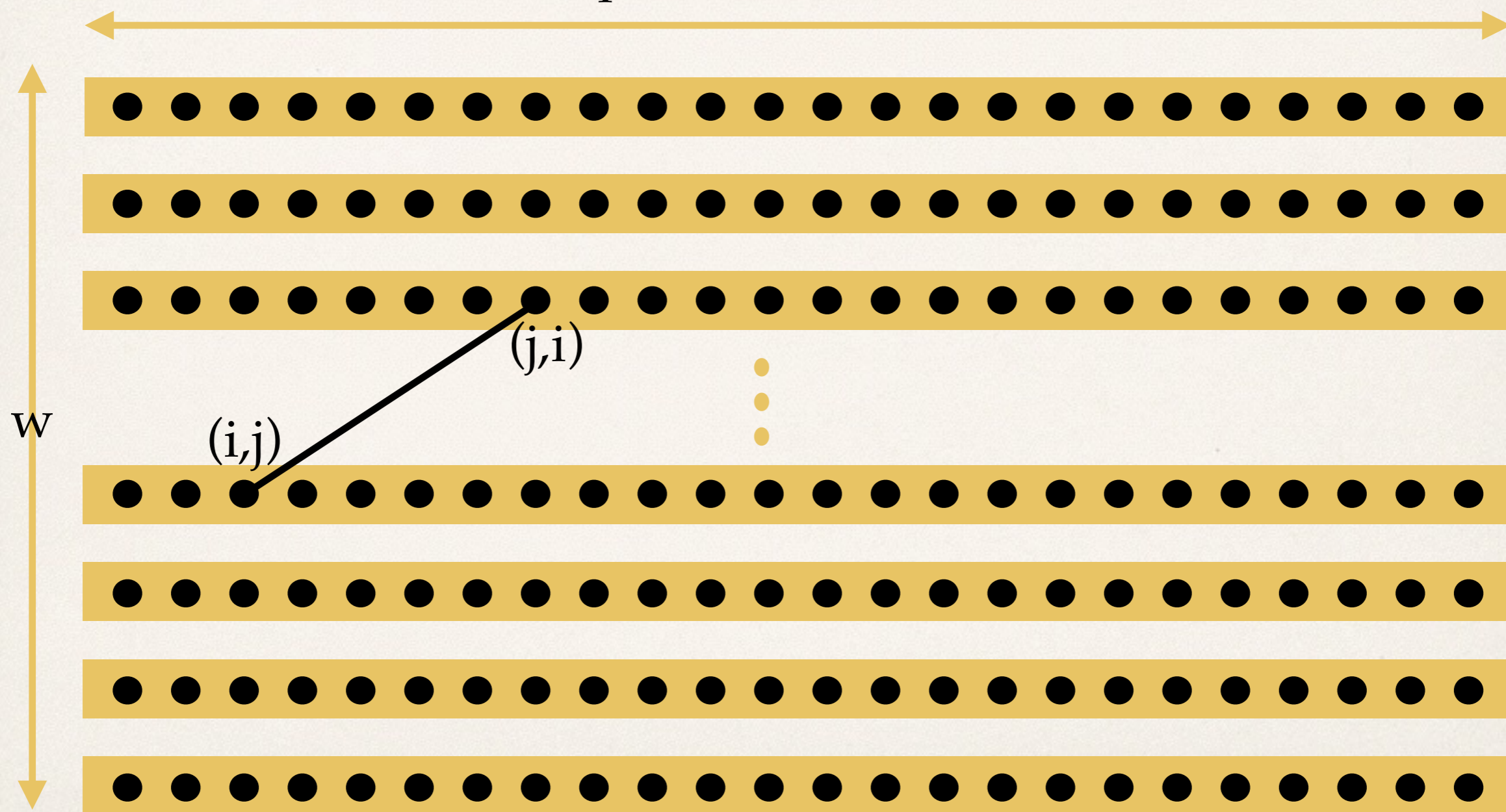


# Graphs with $tw = \Omega(tcw^2)$



# Graphs with $tw = \Omega(tcw^2)$

cliques on  $w$  vertices



# Proving lower bound for $tw$

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- ❖ Bramble  $\mathcal{B}$  of  $G$ : a collection of connected subgraph of  $G$ , mutually “touching” each other, i.e. intersecting or adjacent.
- ❖ Order of Bramble  $\mathcal{B}$ : minimum size of a hitting set
- ❖ THM [Seymour and Thomas 93]:  $tw \geq$  order of any bramble - 1
- ❖ Goal: construct a bramble whose order is  $w^2/100$

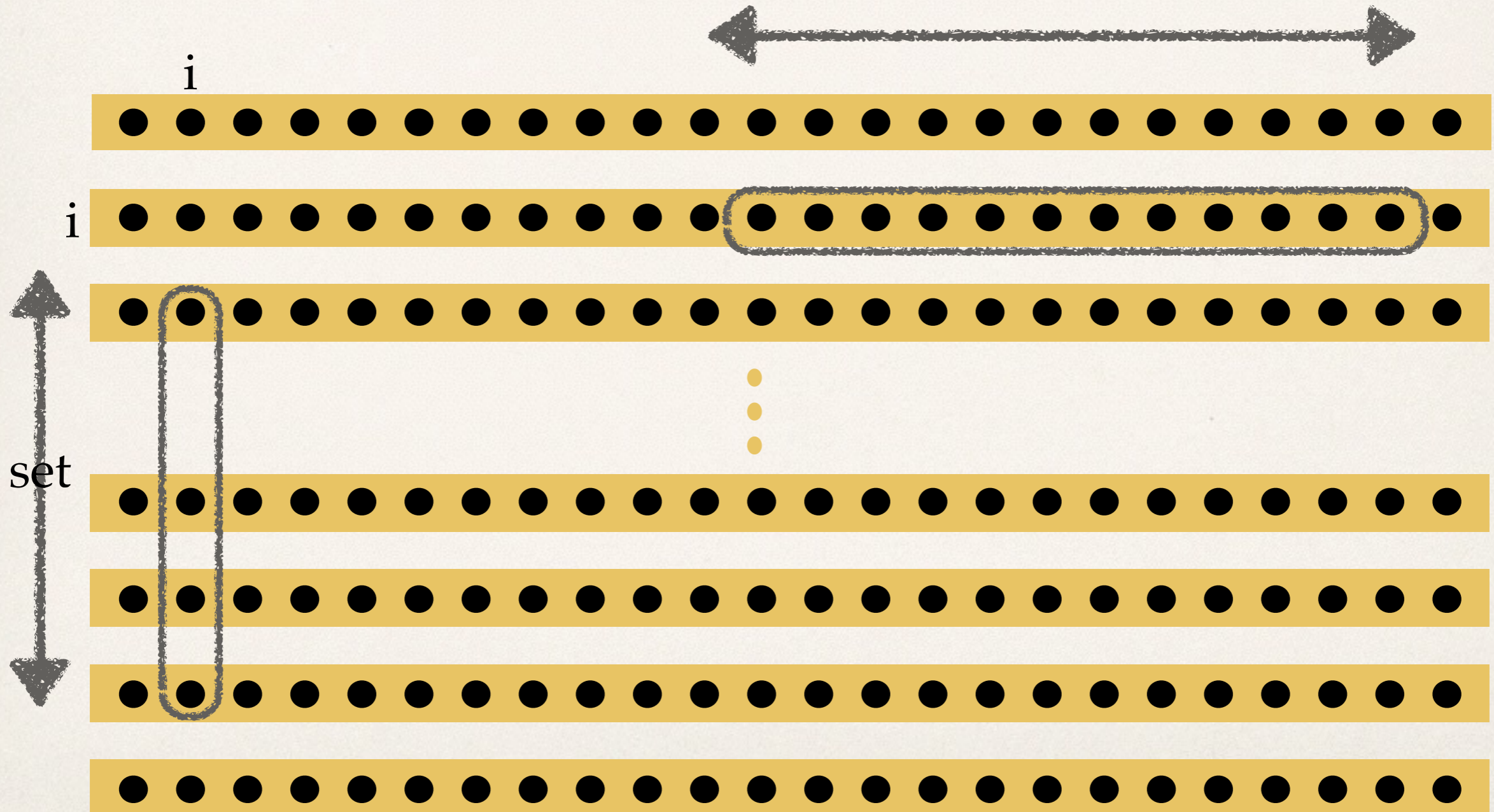
Our bramble  $\mathcal{B}$ :  $\forall i \in [w], \forall \text{set} \subseteq [w] \setminus i$  of size  $w/2$ ,

$\mathcal{B}$  contains the induced graph on  $\{(i,j)(j,i): j \in \text{set}\}$

- each, connected? ✓

- mutually touching? ✓

- needs at least  $w^2/100$  to hit all of them?  
set

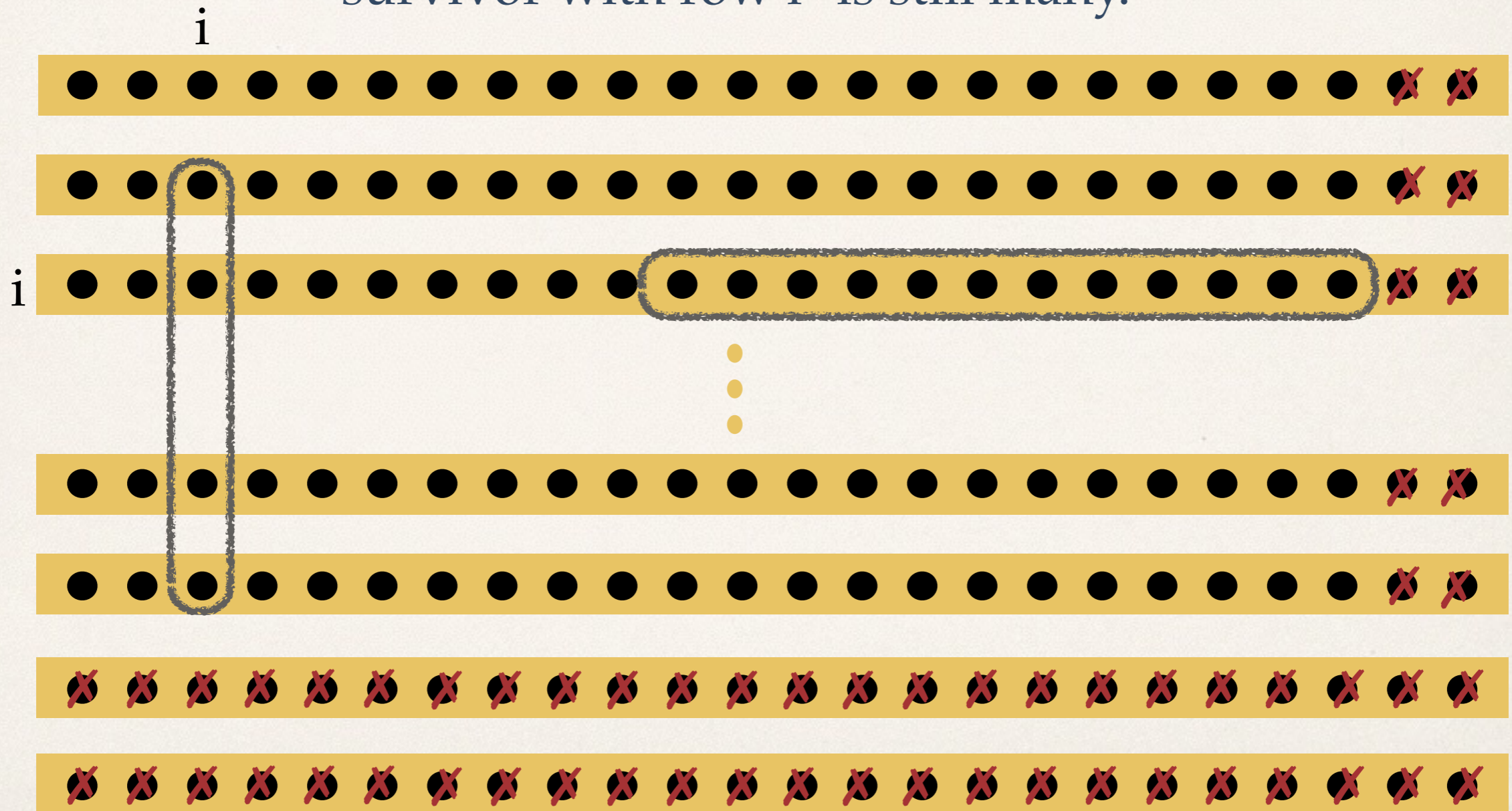


Let  $X$  be a hitting set  $< w^2/100$

What if  $X$  is randomly distributed...

In real life:

- you can find **many** rows "i" where still many vertices survive.
- among such "i", you can find **one** column  $i^*$  whose common survivor with row  $i^*$  is still many.



# Further Questions

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- ❖ For problems hard on graphs with small  $tw$ :  
are there problems showing different computational behavior on small  $pw$  and small  $tcw$ ? e.g. CDC/CVC and boolean CSP
- ❖ Our algorithms run in time  $k^{\text{poly}(k)}$   
Better running time? Or optimal?  
further conditions on graphs to accelerate the runtime?
- ❖ 2-approximation runs in  $w^{O(w^2)}$ .  
Faster algorithm? exact computation?
- ❖ In the end, is tree-cut width an interesting graph

Thanks!